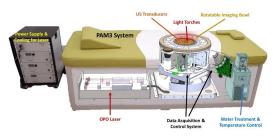
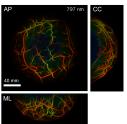




Photoacoustic & Ultrasonic Tomography for Breast Cancer Imaging

Felix Lucka (he/him/his) & the PAMMOTH team



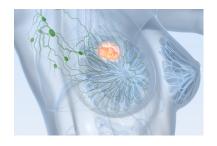


**3rd IMA Conference on Inverse Problems from Theory to Application** 3 May 2022

# **Motivation: Breast Cancer Imaging**

# Most common cause of cancer death in women worldwide.

- 25% of all cancer cases in women
- 15% of all cancer deaths in women

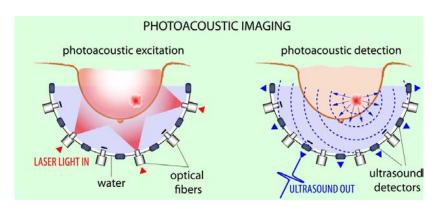


Despite advances in early detection and diagnosis:

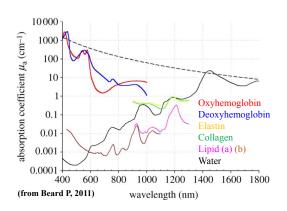
Urgent need for novel imaging techniques providing higher specificity, contrast and image resolution than X-ray mammography at lower costs than MRI.

## **Quantitative Photoacoustic Breast Imaging**

- hybrid imaging: "light in, sound out"
- non-ionizing, near-infrared radiation
- quantitative images of optical properties
- novel diagnostic information



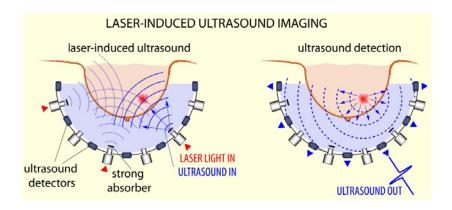
# **Photoacoustic Imaging: Spectral Properties**



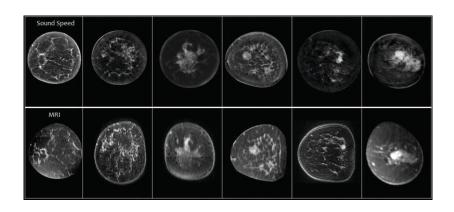
- different wavelengths allow quantitative spectroscopic examinations.
- gap between oxygenated and deoxygenated blood.

# Quantitative Ultrasonic Breast Imaging

- "sound in, sound out"
- different from conventional US but as safe
- quantitative images of acoustic properties
- novel diagnostic information



# **Speed of Sound vs MRI Images**

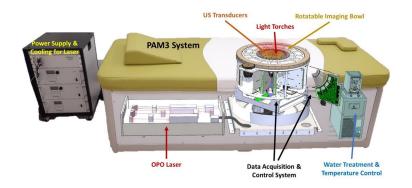


#### Taken from:



Duric, Littrup, 2017. Breast Ultrasound Tomography, IntechOpen.

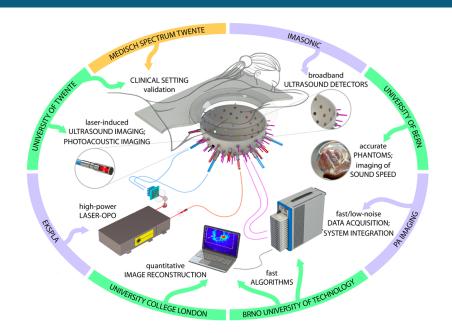
## Photoacoustic and Ultrasonic Mammography Scanner



# Aim: novel diagnostic information from high resolution maps of optical and acoustic properties

- 512 US transducers on rotatable half-sphere
- 40 optical fibers for photoacoustic excitation
- fully 3D, isotropic resolution ≤ 0.5mm

#### The PAMMOTH Team



## **Our Contributions**

#### simulation studies for

- ultrasonic transducer specification
- light excitation design
- sensing pattern design
- measurement protocol design

#### reconstruction algorithm design:

- accuracy vs. computational time/resources/complexity
- scanner modelling
- assist high performance computing implementation

#### assist phantom & calibration design

process data, refine measurement procedures

# Mathematical Modelling (simplified)

## Quantitative Photoacoustic Tomography (QPAT)

radiative transfer equation (RTE) + acoustic wave equation

$$(v \cdot \nabla + \mu_{a}(x) + \mu_{s}(x)) \phi(x, v) = q(x, v) + \mu_{s}(x) \int \Theta(v, v') \phi(x, v') dv',$$

$$p^{PA}(x, t = 0) = p_{0} := \Gamma(x) \mu_{a}(x) \int \phi(x, v) dv, \qquad \partial_{t} p^{PA}(x, t = 0) = 0$$

$$(c(x)^{-2} \partial_{t}^{2} - \Delta) p^{PA}(x, t) = 0, \qquad f^{PA} = Mp^{PA}$$

## **Ultrasound Tomography (UST)**

$$(c(x)^{-2}\partial_t^2 - \Delta)p_i^{US}(x,t) = s_i(x,t), \qquad f_i^{US} = M_i p_i^{US}, \qquad i = 1,\ldots,n_s$$

#### Step-by-step inversion

- 1.  $f^{US} \rightarrow c$ : acoustic parameter identification from boundary data.
- 2.  $f^{PA} \rightarrow p_0$ : acoustic initial value problem with boundary data.
- 3.  $p_0 \rightarrow \mu_a$ : optical parameter identification from internal data.

## Reconstruction of Initial Photoacoustic Pressure

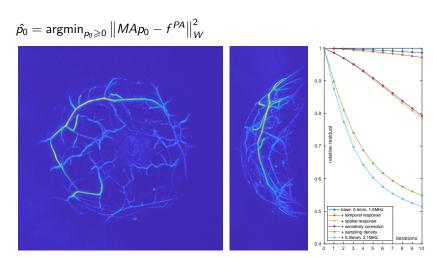
$$(c(x)^{-2}\partial_t^2 - \Delta)p^{PA}(x,t) = 0, \quad p^{PA}(x,t=0) = p_0, \quad f^{PA} = Mp^{PA}$$

- ✓ linear inverse problem  $f^{PA} = MAp_0$ , moderately ill-posed.
- √ variational approach

$$\hat{p_0} = \underset{p_0 \in \mathcal{C}}{\operatorname{argmin}} \left\| MAp_0 - f^{PA} \right\|_W^2 + \mathcal{R}(p_0)$$

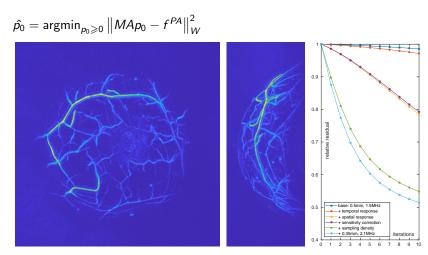
- √ first order optimization with early stopping
  - ! model acoustic properties, model discrepancies
  - ! model /calibrate sensors: sensitivity, impulse response, angular sensitivity, ...
  - ! parameter choices, image artifacts,...
  - ! numerical wave simulations: broadband up to  $\geqslant 1.5 \text{MHz}, \leqslant 0.5 \text{mm}$

# Healthy volunteer, 797nm, baseline



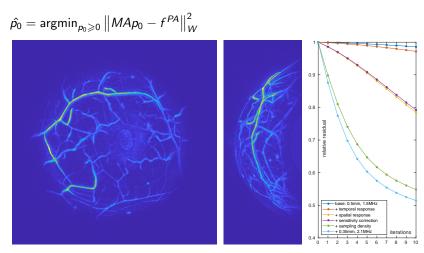
single wave simulation on 0.50mm: 2min 20; 10 iterations: 1h 20min

## Healthy volunteer, 797nm, add impulse response



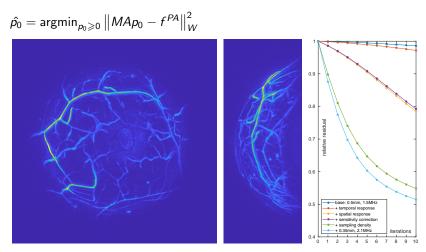
single wave simulation on 0.50mm: 2min 20; 10 iterations: 1h 20min

# Healthy volunteer, 797nm, add spatial response



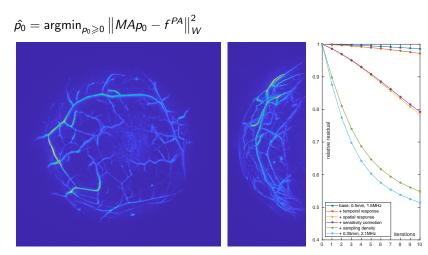
single wave simulation on 0.50mm: 2min 20; 10 iterations: 1h 20min

# Healthy volunteer, 797nm, add sensitivity



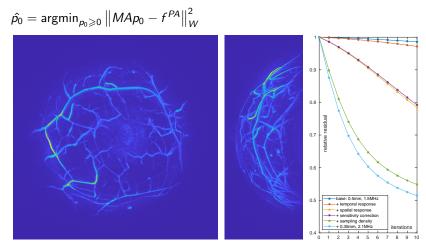
single wave simulation on 0.50mm: 2min 20; 10 iterations: 1h 20min

# Healthy volunteer, 797nm, add sampling density



single wave simulation on 0.50mm: 2min 20; 10 iterations: 1h 20min

## Healthy volunteer, 797nm, increase resolution/bandwidth



single wave simulation on 0.35mm: 12min 10; 10 iterations: 4h 8min

## **UST** Reconstruction Approaches

$$(c(x)^{-2}\partial_t^2 - \Delta)p_i^{US}(x,t) = s_i(x,t), \qquad f_i^{US} = M_i p_i^{US} \qquad i = 1, \dots, n_{src}$$

Travel time tomography: geometrical optics approximation.

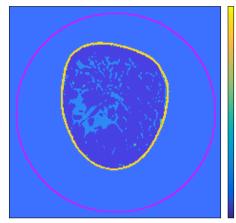
- √ robust & computationally efficient
  - ! valid for high frequencies (attenuation!), low res, lots of data
- **Javaherian**, L, Cox, 2020. Refraction-corrected ray-based inversion for three-dimensional ultrasound tomography of the breast, *Inverse Problems*.

Full waveform inversion (FWI): fit full wave model to all data.

- ✓ high res from little data, transducer modelling, constraints
  - ! many wave simulations, complex numerical optimization
- low TRL but already used in 2D systems
- Pérez-Liva, Herraiz, Udías, Miller, Cox, Treeby 2017. Time domain reconstruction of sound speed and attenuation in ultrasound computed tomography using full wave inversion, *JASA*.

## **FWI Illustration in 2D**

## SOS ground truth $c^{true}$

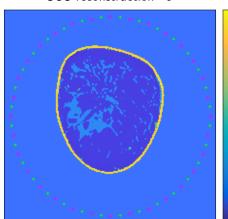


color range 1450 - 1670 m/s

- 1mm resolution
- 222<sup>2</sup> voxel
- 836 voxels on surface (pink)
- TTT would need 836<sup>2</sup> source-receiver combos for high res result

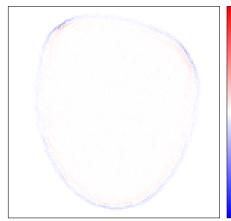
## FWI Illustration in 2D: 32 Sensors, 32 Receivers





color range 1450 - 1670 m/s

reconstruction error  $c^{true} - c^{rec}$ 



color range -50 - 50 m/s

$$\min_{c \in \mathcal{C}} \sum_{i}^{n_{src}} \mathcal{D}\left(M_{i} A^{-1}(c) s_{i}, f_{i}^{\delta}\right)$$

$$\nabla_{c} \mathcal{D}\left(f(c), f^{\delta}\right) = 2 \int_{0}^{T} \frac{1}{c(x)^{3}} \left(\frac{\partial^{2} p(x, t)}{\partial t^{2}}\right) q^{*}(x, t)$$

- !  $2 \times n_{src}$  wave simulations per gradient
- ! computationally & stochastically efficient gradient estimator
- ! memory requirements of gradient computation
- ! slow convergence and local minima
- ! computational resources

$$\min_{c \in \mathcal{C}} \sum_{i}^{n_{src}} \mathcal{D}\left(M_{i} A^{-1}(c) s_{i}, f_{i}^{\delta}\right)$$

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  - $\longrightarrow$  stochastic quasi-newton optimization (SL-BFGS)
- ! computationally & stochastically efficient gradient estimator
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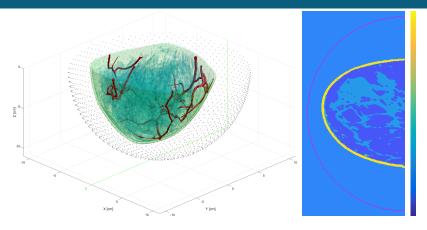
- !  $2 \times n_{src}$  wave simulations per gradient
  - → stochastic quasi-newton optimization (SL-BFGS)
- ! computationally & stochastically efficient gradient estimator
  - $\longrightarrow$  source encoding for time-invariant systems
- ! memory requirements of gradient computation
  - → time-reversal based gradient computation
- ! slow convergence and local minima
  - $\longrightarrow$  coarse-to-fine multigrid schemes
- ! computational resources

$$\min_{c \in \mathcal{C}} \sum_{i}^{N_{src}} \mathcal{D}\left(M_{i} A^{-1}(c) s_{i}, f_{i}^{\delta}\right)$$

$$\nabla_{c} \mathcal{D}\left(f(c), f^{\delta}\right) = 2 \int_{0}^{T} \frac{1}{c(x)^{3}} \left(\frac{\partial^{2} p(x, t)}{\partial t^{2}}\right) q^{*}(x, t)$$

- !  $2 \times n_{src}$  wave simulations per gradient
  - → stochastic quasi-newton optimization (SL-BFGS)
- ! computationally & stochastically efficient gradient estimator
  - $\longrightarrow$  source encoding for time-invariant systems
- ! memory requirements of gradient computation
  - → time-reversal based gradient computation
- ! slow convergence and local minima
  - → coarse-to-fine multigrid schemes
- ! computational resources
  - --- runs on single GPU, can utilize multiple GPUs

# 3D FWI: Setup

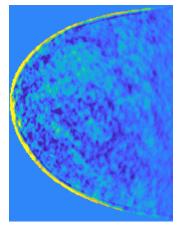


- $\bullet$  color range 1435-1665 m/s
- 3D breast phantom at 0.5mm resolution, 1024 sources and receivers
- $442 \times 442 \times 222$  voxel, 3912 time steps

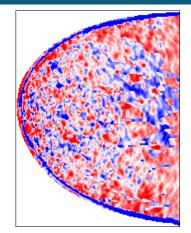


**Yang Lou et al.** Generation of anatomically realistic numerical phantoms for photoacoustic and ultrasonic breast imaging, *JBO*, *2017*.

# Starting point in 24h on desktop with single GPU



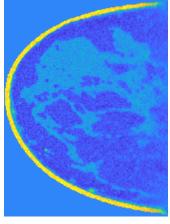
color range 1435 to 1665 m/s



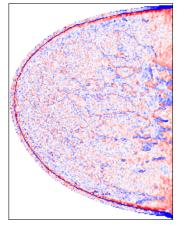
color range -50 to +50 m/s

- single grid
- SGD
- normal single source gradient estimator

# 3D FWI in 24h on desktop with single GPU



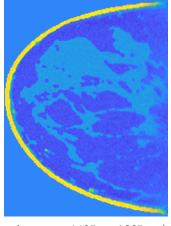
color range 1435 to 1665 m/s



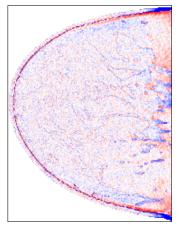
color range -50 to +50 m/s

- multi-grid with 3 level, coarsening factor 2
- SL-BFGS, slowness transform, prog. iter averaging
- time-reversal based source encoding gradient estimator

## 3D FWI in 24h on cluster with 4 GPU



color range 1435 to 1665 m/s



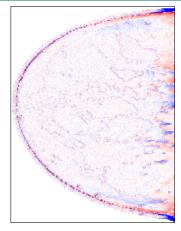
color range -50 to +50 m/s

- multi-grid with 3 level, coarsening factor 2
- SL-BFGS, slowness transform, prog. iter averaging
- time-reversal based source encoding gradient estimator

## 3D FWI in 24h on cluster with 16 GPU



color range 1435 to 1665 m/s



color range -50 to +50 m/s

- multi-grid with 3 level, coarsening factor 2
- SL-BFGS, slowness transform, prog. iter averaging
- time-reversal based source encoding gradient estimator

# FWI for Experimental Data: Where Are We?

- ✓ data from phantom objects, volunteers & patients
- √ ray-based SOS reconstructions
- $\checkmark$  photoacoustic reconstructions  $\rightarrow$  data pre-processing, scanner & transducer modelling, wave simulations
- √ modeling of US protocol, data read-in & pre-processing
  - ! model calibration
  - ! FWI of phantom objects, quantitative evaluation
  - ! FWI of volunteer data
  - ! clinical evaluation

## **Summary & Outlook**

- need for novel breast imaging techniques
- photoacoustic (PAT) and ultrasound tomography (UST) give access to high-quality images of optical and acoustic tissue properties
- combined PAT+UST scanner designed & build
- evaluation on data from phantoms, volunteers & patients
- PAT reconstructions work well
- proof-of-concept studies of TD-FWI for high resolution 3D UST
- realization of FWI for experimental data





# Thank you for your attention!



L, Pérez-Liva, Treeby, Cox, 2021. High Resolution 3D Ultrasonic Breast Imaging by Time-Domain Full Waveform Inversion, Inverse Problems 38(2).











## Challenges of High-Resolution FWI in 3D

$$\min_{c \in \mathcal{C}} \sum_{i}^{n_{src}} \mathcal{D}\left(f_{i}(c), f_{i}^{\delta}\right) \quad s.t. \quad f_{i}(c) = M_{i}A^{-1}(c)s_{i}$$

$$\nabla_{c}\mathcal{D}\left(f(c), f^{\delta}\right) = 2\int_{0}^{T} \frac{1}{c(x)^{3}} \left(\frac{\partial^{2} p(x, t)}{\partial t^{2}}\right) q^{*}(x, t)$$

#### PAMMOTH scanner example:

- 0.5mm res: comp grid  $560 \times 560 \times 300$  voxel = 94M, ROI = 7M
- 1024 transducers, 4000 time samples (multiple sources);

#### Gradient computation:

- 1 wave sim:  $\sim$ 30 min.
- ! 2 wave sim per source,  $n_{src} = 1024 \rightarrow 20$  days per gradient. stochastic gradient methods  $\rightarrow$  60 min per gradient
- ! storage of forward field in ROI:  $\sim$  200GB. time-reversal based gradient computation  $\rightarrow$  5 25GB.

# **Stochastic Gradient Optimization**

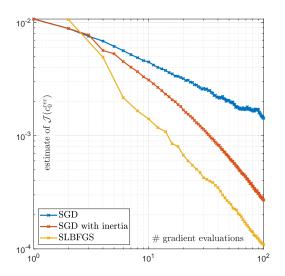
$$\mathcal{J} := n_{src}^{-1} \sum_{i}^{n_{src}} \mathcal{D}_i(c) := n_{src}^{-1} \sum_{i}^{n_{src}} \mathcal{D}\left(M_i A^{-1}(c) s_i, f_i^{\delta}\right)$$

approx  $\nabla \mathcal{J}$  by  $|\mathcal{S}|^{-1} \sum_{j \in \mathcal{S}} \nabla \mathcal{D}_j(c)$ ,  $\mathcal{S} \subset \{1, \dots, n_{src}\}$  predetermined.  $\rightarrow$  incremental gradient, ordered sub-set methods

Instance of **finite sum minimization** similar to **training in machine learning**. Use **stochastic gradient descent (SGD)**:

- momentum, gradient/iterate averaging (SAV, SAGA), variance reduction (SVRG), choice of step size, mini-batch size
- include non-smooth regularizers (SPDHG, SADMM)
- quasi-Newton-type methods, e.g., stochastic L-BFGS
- **Bottou, Curtis, Nocedal.** Optimization Methods for Large-Scale Machine Learning, arXiv:1606.04838.
  - **Fabien-Ouellet, Gloaguen, Giroux, 2017.** A stochastic L-BFGS approach for full-waveform inversion, *SEG*.

#### **Stochastic Gradient Optimization**



### **Gradient Estimates: Sub-Sampling vs Source Encoding**

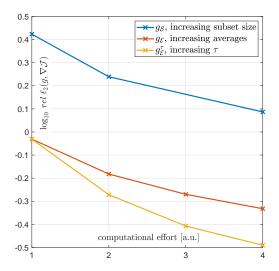
Computationally & stochastically efficient gradient estimator?

**Source Encoding** for linear PDE constraints:

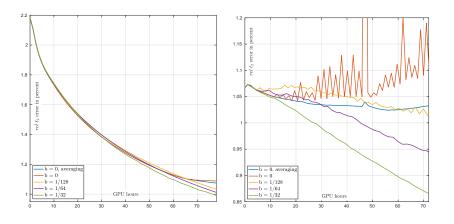
$$\begin{split} \text{Let} \quad \hat{s} := \sum_{i}^{n_{srt}} w_i s_i, \quad \hat{f}^\delta := \sum_{i}^{n_{srt}} w_i f_i^\delta, \quad \text{with} \quad \mathbb{E}\left[w\right] = 0, \ \mathbb{C}\text{ov}[w] = I, \\ \text{then} \quad \mathbb{E}\left[\nabla \left\| MA^{-1}(c)\hat{s} - \hat{f}^\delta \right\|_2^2\right] = \nabla \sum_{i}^{n_{src}} \left\| MA^{-1}(c)s_i - f_i^\delta \right\|_2^2 \end{aligned}$$

- related to covariance trace estimators
- Rademacher distribution ( $w_i = \pm 1$  with equal prob)
- ullet add time-shifting for time-invariant PDEs o variance control
- can be turned into scanning strategy
- Haber, Chung, Herrmann, 2012. An effective method for parameter estimation with PDE constraints with multiple right-hand sides, *SIAM J. Optim.*

#### **Stochastic Gradient Estimates**



# **Delayed Source Encoding**



#### **Time-Reversal Gradient Computations**

#### Avoid storage of forward fields!

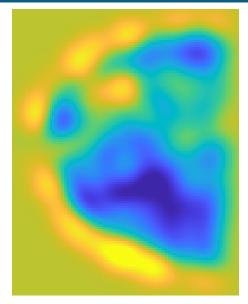
$$(c(x)^{-2}\partial_t^2 - \Delta)p(x,t) = s(x,t), \quad in \mathbb{R}^d \times [0,T]$$

$$\nabla_c \mathcal{D} = 2 \int_0^T \frac{1}{c(x)^3} \left(\frac{\partial^2 p(x,t)}{\partial t^2}\right) q^*(x,t)$$

**Idea:** ROI  $\Omega$ , supp $(s) \in \Omega^c \times [0, T]$ . As  $p(x, 0) = p(x, T) = \partial_t p(x, 0) = \partial_t p(x, T) = 0$  in  $\Omega$ , p(x, t) can be reconstructed from p(x, t) on  $\partial \Omega \times [0, T]$  by **time-reversal (TR)**.

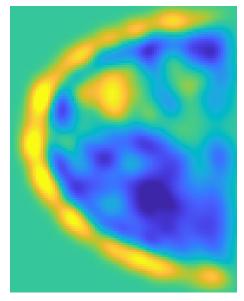
- store fwd fields on ROI boundary during forward wave simulation
- interleave backward (adjoint) simulation with TR of boundary data
- 3 instead of 2 wave simulations (unless 2 GPUs used).
- code up efficiently
- multi-layer boundary increases accuarcy for pseudospectral method

- easy due to regular grids in space and time
- coarsening by 2: (in principle)
   speed up of 16
- most basic multi-grid usage for now: initialization



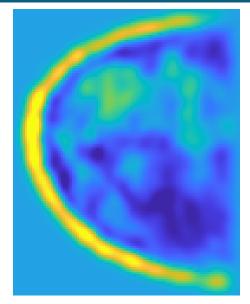
level 6: upsampled from 5.66mm.

- easy due to regular grids in space and time
- coarsening by 2: (in principle)
   speed up of 16
- most basic multi-grid usage for now: initialization



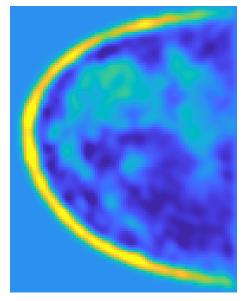
level 5: upsampled from 4mm.

- easy due to regular grids in space and time
- coarsening by 2: (in principle) speed up of 16
- most basic multi-grid usage for now: initialization



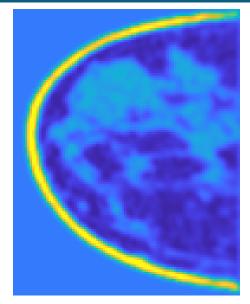
level 4: upsampled from 2.83mm.

- easy due to regular grids in space and time
- coarsening by 2: (in principle) speed up of 16
- most basic multi-grid usage for now: initialization



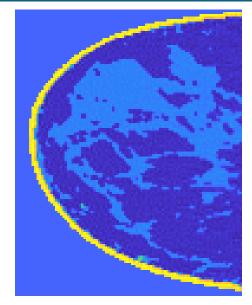
level 3: upsampled from 2mm.

- easy due to regular grids in space and time
- coarsening by 2: (in principle) speed up of 16
- most basic multi-grid usage for now: initialization



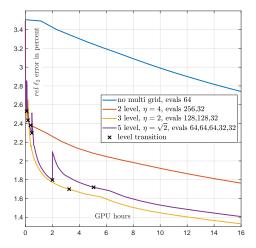
level 2: upsampled from 1.41mm.

- easy due to regular grids in space and time
- coarsening by 2: (in principle) speed up of 16
- most basic multi-grid usage for now: initialization



level 1: resolution 1mm

- easy due to regular grids in space and time
- coarsening by 2: **speed up of 16** (in principle)
- most basic multi-grid usage for now: initialization



# **Utilizing Multiple GPUs**

- average independent gradient estimates to reduce variance
- not be the best way to use multiple GPUs

