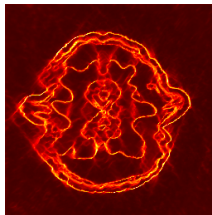


Sample-based Sparse Bayesian Inversion in Biomedical Imaging

Felix Lucka

University College London, UK
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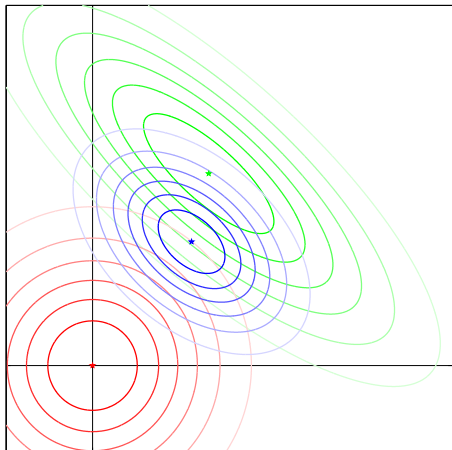
Ill-posed inverse problems with additive Gaussian noise:

$$f = \mathcal{A}(u) + \varepsilon$$

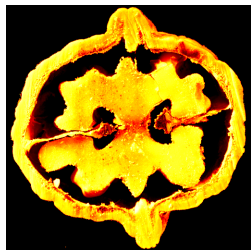
$$p_{\text{like}}(f|u) \propto \exp\left(-\frac{1}{2}\|f - Au\|_{\Sigma_\varepsilon}^2\right)$$

$$p_{\text{prior}}(u) \propto \exp\left(-\lambda\|D^T u\|_2^2\right)$$

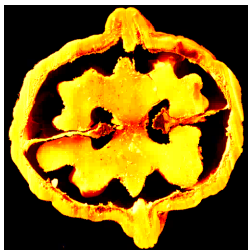
$$p_{\text{post}}(u|f) \propto \exp\left(-\frac{1}{2}\|f - Au\|_{\Sigma_\varepsilon}^2 - \lambda\|D^T u\|_2^2\right)$$



Probabilistic representation allows for a rigorous **quantification of the solution's uncertainties**.



(a) 100%



(b) 10%

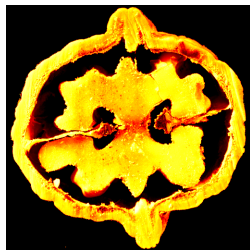


(c) 1%

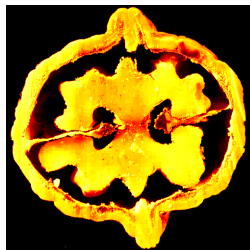
Sparsity a-priori constraints are used in **variational regularization**, **compressed sensing** and **ridge regression**:

$$\hat{u}_\lambda = \underset{u}{\operatorname{argmin}} \left\{ \frac{1}{2} \|f - Au\|_2^2 + \lambda \|D^T u\|_1 \right\}$$

(e.g. *total variation*, *wavelet shrinkage*, *LASSO*,...)



(a) 100%



(b) 10%



(c) 1%

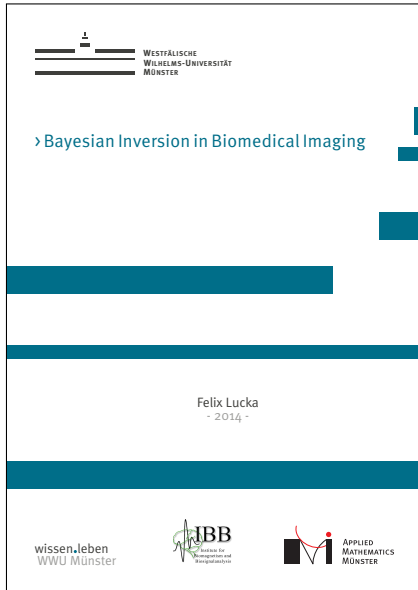
Sparsity a-priori constraints are used in **variational regularization**, **compressed sensing** and **ridge regression**:

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(e.g. *total variation*, *wavelet shrinkage*, *LASSO*,...)

How about sparsity as a-priori information in the Bayesian approach?

- ▶ Submitted 2014, supervised by **Martin Burger** and **Carsten H. Wolters**.
- ▶ Linear inverse problems in **biomedical imaging** applications.
- ▶ Simulated data scenarios and **experimental CT and EEG/MEG** data.
- ▶ **Sparsity** by means of
 - ▶ l_p -norm based priors
 - ▶ **Hierarchical** prior modeling
- ▶ Focus on **Bayesian computation** and application.



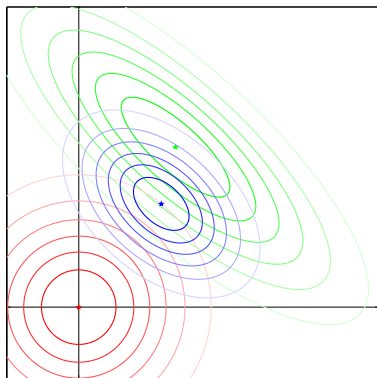
- 1 Introduction: Sparse Bayesian Inversion
- 2 Sparsity by ℓ_p Priors
- 3 Hierarchical Bayesian Modeling
- 4 Discussion, Conclusion and Outlook
- 5 Appendix

$$p_{prior}(\mathbf{u}) \propto \exp\left(-\lambda \|\mathbf{D}^T \mathbf{u}\|_p^p\right), \quad p_{post}(\mathbf{u}|\mathbf{f}) \propto \exp\left(-\frac{1}{2} \|\mathbf{f} - \mathbf{A}\mathbf{u}\|_{\Sigma_\epsilon^{-1}}^2 - \lambda \|\mathbf{D}^T \mathbf{u}\|_p^p\right)$$

Decrease p from 2 to 0 and stop at $p = 1$ for convenience.

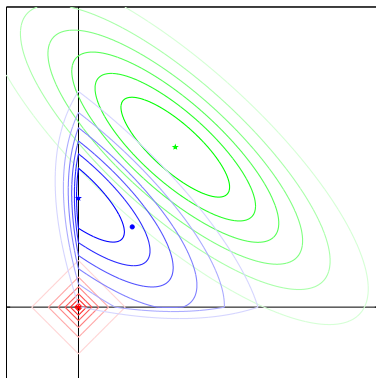
$$p_{\text{prior}}(\mathbf{u}) \propto \exp\left(-\lambda \|\mathbf{D}^T \mathbf{u}\|_p^p\right), \quad p_{\text{post}}(\mathbf{u}|\mathbf{f}) \propto \exp\left(-\frac{1}{2} \|\mathbf{f} - \mathbf{A}\mathbf{u}\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|\mathbf{D}^T \mathbf{u}\|_p^p\right)$$

Decrease p from 2 to 0 and stop at $p = 1$ for convenience.



$$\exp\left(-\lambda \|\mathbf{D}^T \mathbf{u}\|_2^2\right)$$

$$\exp\left(-\frac{1}{2} \|\mathbf{f} - \mathbf{A}\mathbf{u}\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|\mathbf{D}^T \mathbf{u}\|_2^2\right)$$



$$\exp\left(-\lambda \|\mathbf{D}^T \mathbf{u}\|_1\right)$$


$$\exp\left(-\frac{1}{2} \|\mathbf{f} - \mathbf{A}\mathbf{u}\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|\mathbf{D}^T \mathbf{u}\|_1\right)$$


$$p_{post}(u|f) \propto \exp\left(-\frac{1}{2}\|f - Au\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda\|D^T u\|_1\right)$$


Aims: Bayesian inversion in high dimensions ($n \rightarrow \infty$).

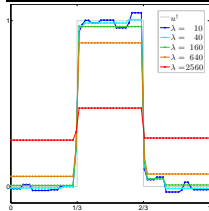
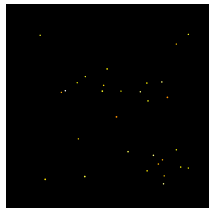
Priors: Simple ℓ_1 , total variation (TV), Besov space priors.

Starting points:

 **Lassas & Siltanen, 2004.** *Can one use total variation prior for edge-preserving Bayesian inversion?* *Inverse Problems*, 20.

 **Lassas, Saksman & Siltanen, 2009.** *Discretization invariant Bayesian inversion and Besov space priors.* *Inverse Problems and Imaging*, 3(1).

 **Kolehmainen, Lassas, Niinimäki & Siltanen, 2012.** *Sparsity-promoting Bayesian inversion.* *Inverse Problems*, 28(2).



Task: Monte Carlo integration by samples from

$$p_{post}(u|f) \propto \exp\left(-\frac{1}{2}\|f - Au\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|D^T u\|_1\right)$$

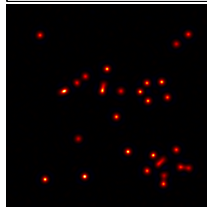
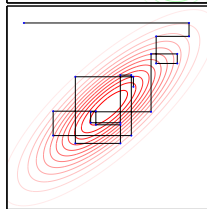
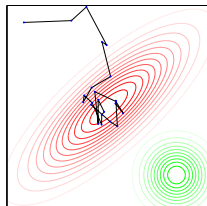
Problem: Standard Markov chain Monte Carlo (MCMC) sampler (Metropolis-Hastings) inefficient for large n or λ .

Contributions:

- ▶ Development of **explicit single component Gibbs sampler**.
- ▶ **Tedious** implementation for different scenarios.
- ▶ Still **efficient in high dimensions** ($n > 10^6$).
- ▶ Detailed evaluation and comparison to MH.

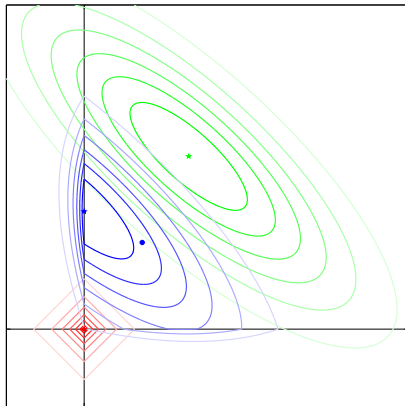


L, 2012. *Fast Markov chain Monte Carlo sampling for sparse Bayesian inference in high-dimensional inverse problems using L1-type priors.* *Inverse Problems*, 28(12):125012.



$$\hat{u}_{\text{MAP}} := \operatorname{argmax}_{u \in \mathbb{R}^n} \{ p_{\text{post}}(u|f) \} \quad \text{vs.} \quad \hat{u}_{\text{CM}} := \int u p_{\text{post}}(u|f) \, du$$

- ▶ CM preferred in theory, dismissed in practice.
- ▶ MAP discredited by theory, chosen in practice.

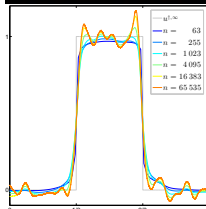
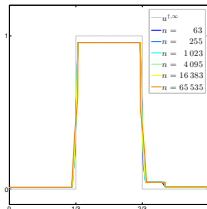
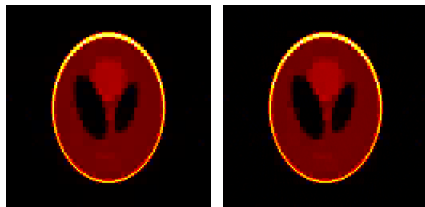
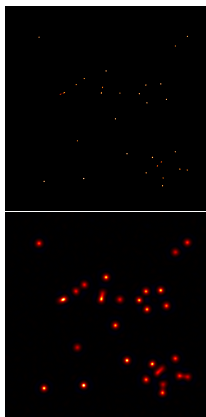


$$\hat{u}_{\text{MAP}} := \underset{u \in \mathbb{R}^n}{\text{argmax}} \{ p_{\text{post}}(u|f) \} \quad \text{vs.} \quad \hat{u}_{\text{CM}} := \int u p_{\text{post}}(u|f) \, du$$

- ▶ CM preferred in theory, dismissed in practice.
- ▶ MAP discredited by theory, chosen in practice.

However:

- ▶ MAP results looks/performs better or similar to CM.
- ▶ Gaussian priors: MAP = CM. Funny coincidence?
- ▶ Theoretical argument has a logical flaw.



$$\hat{u}_{\text{MAP}} := \underset{u \in \mathbb{R}^n}{\operatorname{argmax}} \{ p_{\text{post}}(u|f) \} \quad \text{vs.} \quad \hat{u}_{\text{CM}} := \int u p_{\text{post}}(u|f) du$$

- ▶ CM preferred in theory, dismissed in practice.
- ▶ MAP discredited by theory, chosen in practice.

Contributions:

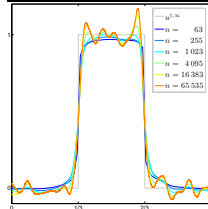
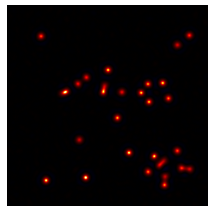
- ▶ Theoretical rehabilitation of MAP.
- ▶ Key: **Bayes cost functions based on Bregman distances.**
- ▶ Gaussian case consistent in this framework.



Burger & L, 2014. *Maximum a posteriori estimates in linear inverse problems with log-concave priors are proper Bayes estimators*, *Inverse Problems*, 30(11):114004.



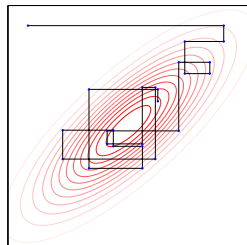
Helin & Burger, 2015. *Maximum a posteriori probability estimates in infinite-dimensional Bayesian inverse problems*, *Inverse Problems*, 31(8)



$$p_{\text{prior}}(u) \propto \exp(-\lambda \|D^T u\|_1)$$

Limitations:

- ▶ D must be diagonalizable (**synthesis** priors):
- ▶ ℓ_p^q -prior: $\exp(-\lambda \|D^T u\|_p^q)$? TV in 2D/3D?
- ▶ Non-negativity or other hard-constraints?



Contributions:

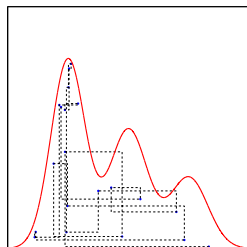
- ▶ Replace explicit by **generalized slice sampling**.
- ▶ Implementation & evaluation for most common priors.



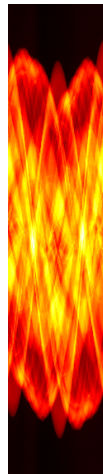
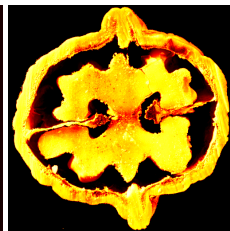
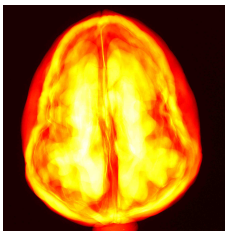
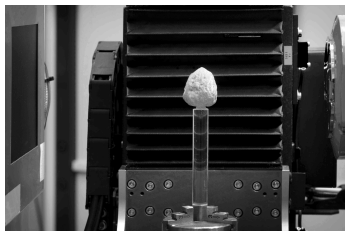
Neal, 2003. *Slice Sampling*. *Annals of Statistics* 31(3)



L, 2015. *Fast Gibbs sampling for high-dimensional Bayesian inversion*. (in preparation)



- ▶ Cooperation with Samuli Siltanen, Esa Niemi et al.
- ▶ Implementation of MCMC methods for Fanbeam-CT.
- ▶ Besov and TV prior; non-negativity constraints.
- ▶ Stochastic noise modeling.
- ▶ Bayesian perspective on limited angle CT.



Use the data set for your own work:

<http://www.fips.fi/dataset.php> (documentation: [arXiv:1502.04064](https://arxiv.org/abs/1502.04064))



(a) MAP



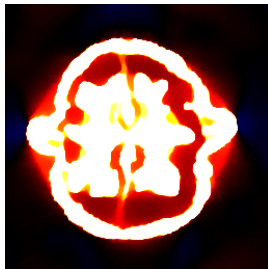
(b) MAP, special color scale



(c) CStd



(d) CM



(e) CM, special color scale



(f) CM of $\|\nabla u\|_2$



(a) MAP, full



(b) CM, full



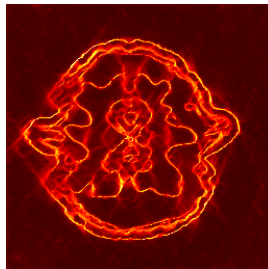
(c) CStd, full



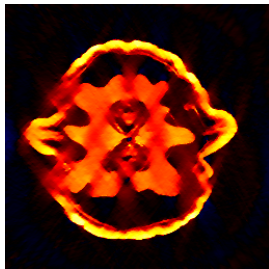
(d) MAP, limited



(e) CM, limited



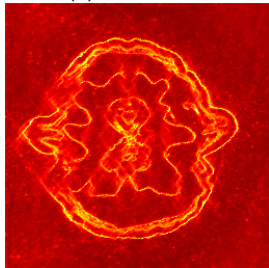
(f) CStd, limited



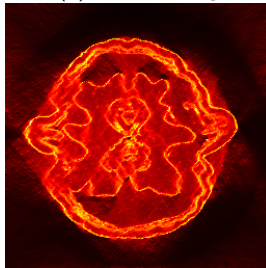
(a) CM, uncon



(b) CM, non-neg



(c) CStd, uncon



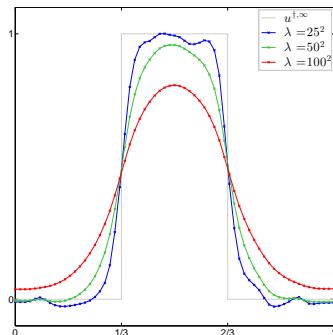
(d) CStd, non-neg

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Gaussian increment prior:

$$p_{\text{prior}}(\mathbf{u}) \propto \prod_i \exp\left(-\frac{(u_{i+1} - u_i)^2}{\gamma}\right)$$

- ▶ Gaussian variables take values on a characteristic scale, determined by γ .
- ▶ Similar amplitudes are likely, sparsity (= outliers) is unlikely.

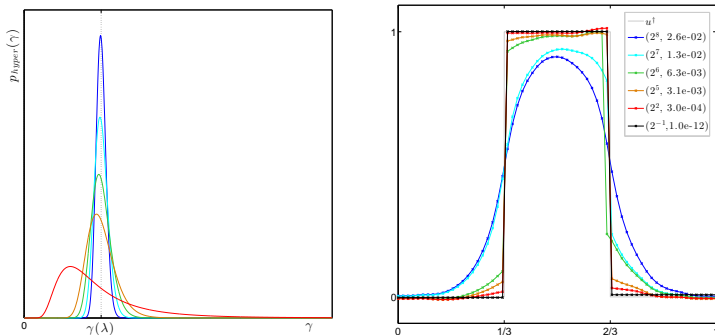


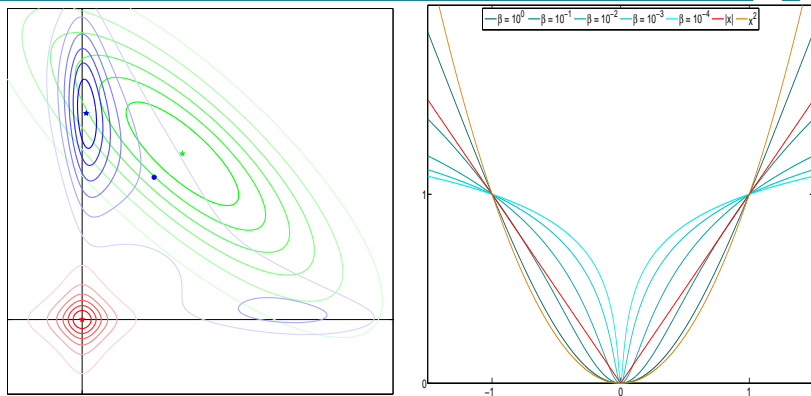
Conditionally Gaussian increment prior:

$$p_{\text{prior}}(\mathbf{u}|\boldsymbol{\gamma}) \propto \prod_i \exp\left(-\frac{(u_{i+1} - u_i)^2}{\gamma_i}\right)$$

Scale-invariant hyperprior to approximate un-informative γ_i^{-1} prior:

$$p_{\text{hyper}}(\gamma_i) \propto \gamma_i^{-(\alpha+1)} \exp\left(-\frac{\beta}{\gamma_i}\right), \quad \text{inverse gamma distribution}$$





Implicit prior is a Student's t -prior with $\nu = 2\alpha$, $\theta = \beta/(2\alpha)$:

$$p_{\text{prior}}(u) \propto \prod_i \left(1 + \frac{u_i^2}{\nu\theta} \right)^{-\frac{\nu-1}{2}}$$

$$p_{\text{post}}(u|f) \propto \exp \left(-\frac{1}{2} \|f - Au\|_{\Sigma_\epsilon^{-1}}^2 - \frac{\nu-1}{2} \sum_i \log \left(1 + \frac{u_i^2}{\nu\theta} \right) \right)$$

$$p_{post}(u, \gamma | f) \propto \exp \left(-\frac{1}{2} \|f - Au\|_{\Sigma_\epsilon}^2 - \sum_i^n \left(\frac{u_i^2 + 2\beta}{2\gamma_i} + (\alpha + 1/2) \log(\gamma_i) \right) \right)$$

All computational approaches (optimization or sampling) exploit the **conditional structure**:

- ▶ Fix γ and update u by solving n -dim linear problem.
- ▶ Fix u and update γ by solving n 1-dim non-linear problems.

Major difficulty: Multimodality of posterior.

Heuristic Full-MAP computation:

- ▶ Use MCMC to explore posterior (avoids very sub-optimal local modes).
- ▶ Initialize alternating optimization by local MCMC averages to compute local modes.

No guarantee for finding highest mode but usually an acceptable result.

- ▶ Inversion with **log-concave** priors suffers from systematic depth miss-localization, HBM does not.
- ▶ HBM shows promising results for focal brain networks with **simulated and real data**.



L., Aydin, Vorwerk, Burger, Wolters, 2013. *Hierarchical Fully-Bayesian Inference for Combined EEG/MEG Source Analysis of Evoked Responses: From Simulations to Real Data.*

[BaCI 2013, Geneva.](#)



L., Pursiainen, Burger, Wolters, 2012. *Hierarchical Fully-Bayesian Inference for EEG/MEG combination: Examination of Depth Localization and Source Separation using Realistic FE Head Models.*

[Biomag 2012, Paris](#)



L., Pursiainen, Burger, Wolters, 2012. *Hierarchical Bayesian inference for the EEG inverse problem using realistic FE head models: Depth localization and source separation for focal primary currents.*

[NeuroImage, 61\(4\):1364–1382.](#)

Bayesian Modeling:





- ▶ Sparsity can be modeled in different ways.
- ▶ HBM is an interesting but challenging alternative to ℓ_p priors.
- ▶ Combine ℓ_p -type and hierarchical priors: ℓ_p -hypermodels.

Bayesian Computation:





- ▶ Elementary MCMC samplers may perform very differently.
- ▶ **Contrary to common beliefs** sample-based Bayesian inversion in high dimensions ($n > 10^6$) is feasible if tailored samplers are developed.
- ▶ Fast samplers can be used for **simulated annealing**.
- ▶ Reason for the efficiency of the Gibbs samplers is unclear.
- ▶ **Adaptation, parallelization, multimodality, multi-grid.**

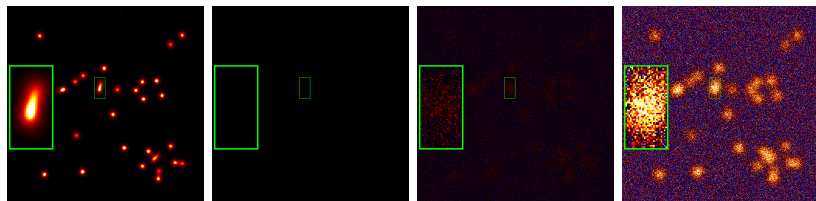
Bayesian Estimation / Uncertainty Quantification

- ▶ MAP estimates are proper Bayes estimators.
- ▶ **But:** Everything **beyond "MAP or CM?"** is far more interesting and can really complement variational approaches.
- ▶ **However:** Extracting information from posterior samples (*data mining*) is a non-trivial (future research) topic.
- ▶ Application studies had **proof-of-concept character** up to now.
- ▶ Specific UQ task to explore full potential of the Bayesian approach.

-  **L., 2014.** *Bayesian Inversion in Biomedical Imaging*
PhD Thesis, University of Münster.
-  **M. Burger, L., 2014.** *Maximum a posteriori estimates in linear inverse problems with log-concave priors are proper Bayes estimators*
Inverse Problems, 30(11):114004.
-  **L., 2012.** *Fast Markov chain Monte Carlo sampling for sparse Bayesian inference in high-dimensional inverse problems using L1-type priors.*
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NeuroImage, 61(4):1364–1382.

Thank you for your attention!

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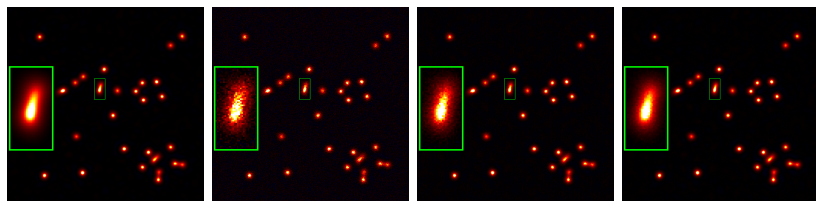


(a) Reference

(b) MH-Iso, 1h

(c) MH-Iso, 4h

(d) MH-Iso, 16h



(e) Reference

(f) SC Gibbs, 1h

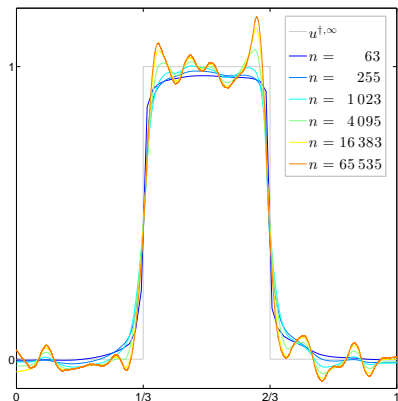
(g) SC Gibbs, 4h

(h) SC Gibbs, 16h

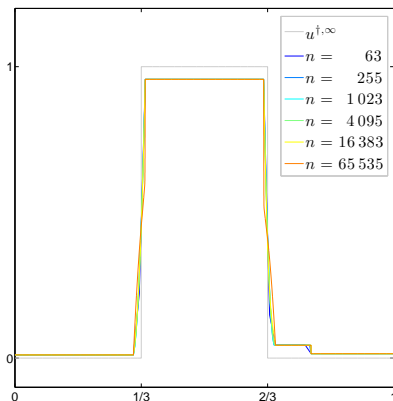
Deconvolution, simple ℓ_1 prior, $n = 513 \times 513 = 263\,169$.

Numerical verification of the discretization dilemma of the TV prior (Lassas & Siltanen, 2004):

- ▶ For $\lambda_n = \text{const.}$, $n \rightarrow \infty$ the TV prior diverges.
- ▶ CM diverges.
- ▶ MAP converges to edge-preserving limit.



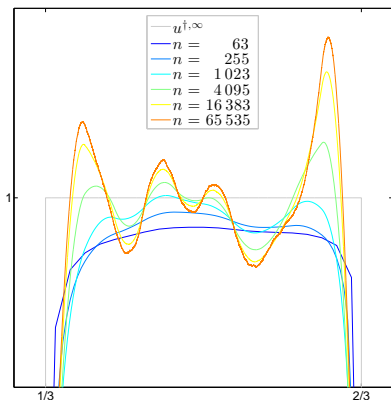
(a) CM by our Gibbs Sampler



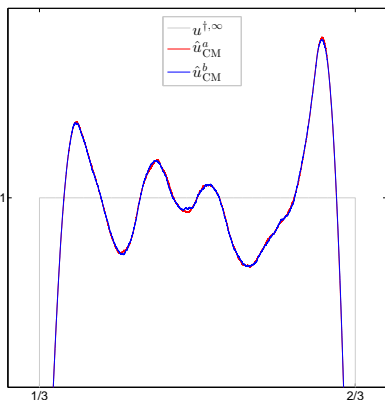
(b) MAP by ADMM

Numerical verification of the discretization dilemma of the TV prior (Lassas & Siltanen, 2004):

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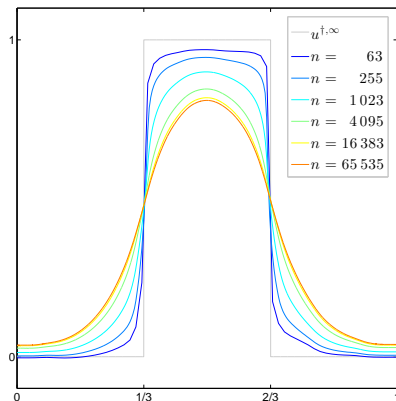
(a) Zoom into CM estimates



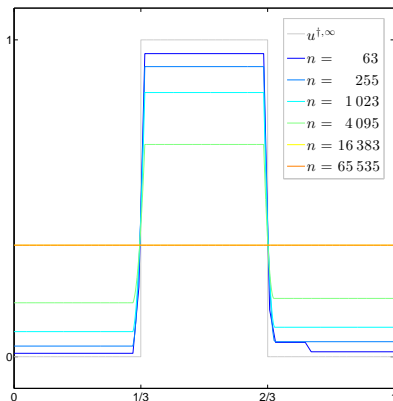
(b) MCMC convergence check

Numerical verification of the discretization dilemma of the TV prior (Lassas & Siltanen, 2004):

- ▶ For $\lambda_n \propto \sqrt{n+1}$, $n \rightarrow \infty$ the TV prior converges to a smoothness prior.
- ▶ CM converges to smooth limit.
- ▶ MAP converges to constant.



(a) CM by our Gibbs Sampler



(b) MAP by ADMM

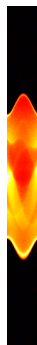
For images dimensions > 1 : No theory yet...but we can compute it.

Test scenario:

- ▶ CT using only 45 projection angles and 500 measurement pixel.



real solution



data f



colormap

For images dimensions > 1 : No theory yet...but we can compute it.



MAP, $n = 64^2$, $\lambda = 500$



CM, $n = 64^2$, $\lambda = 500$

For images dimensions > 1 : No theory yet...but we can compute it.

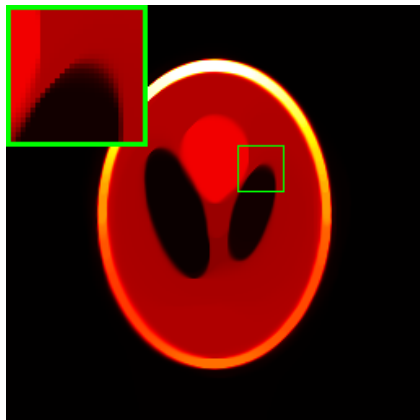


MAP, $n = 128^2$, $\lambda = 500$

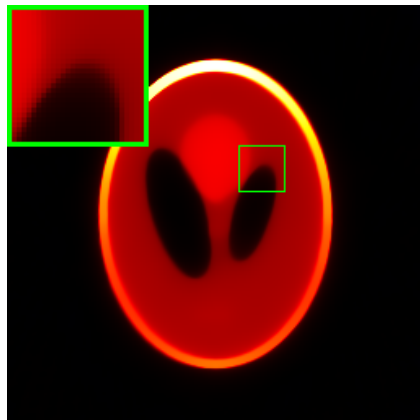


CM, $n = 128^2$, $\lambda = 500$

For images dimensions > 1 : No theory yet...but we can compute it.



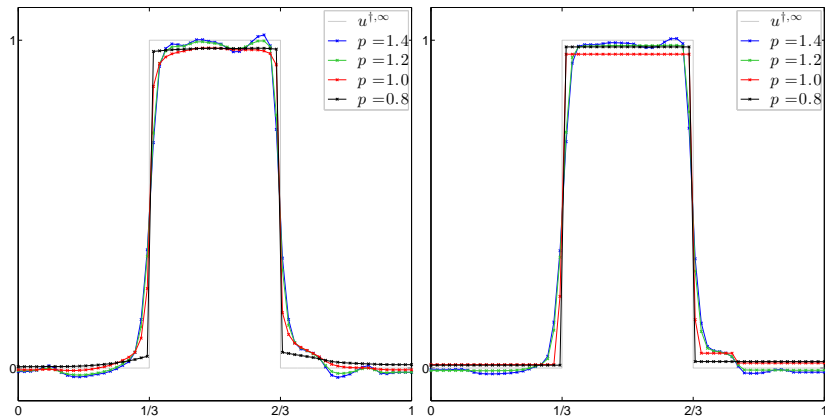
MAP, $n = 256^2$, $\lambda = 500$



CM, $n = 256^2$, $\lambda = 500$

cf. [Louchet, 2008](#), [Louchet & Moisan, 2013](#) for the denoising case, $A = I$.

$$p_{post}(u) \propto \exp\left(-\frac{1}{2}\|f - Au\|_{\Sigma_\epsilon}^2 - \lambda \|D^T u\|_p^p\right)$$



(c) CM (Gibbs-MCMC)

(d) MAP (Simulated Annealing)

An ℓ_1 -type, wavelet-based prior:

$$p_{\text{prior}}(u) \propto \exp(-\lambda \|WV^T u\|_1)$$

motivated by:

-  M. Lassas, E. Saksman, S. Siltanen, 2009. *Discretization invariant Bayesian inversion and Besov space priors.*, *Inverse Probl Imaging*, 3(1).
-  V. Kolehmainen, M. Lassas, K. Niinimäki, S. Siltanen, 2012. *Sparsity-promoting Bayesian inversion*, *Inverse Probl*, 28(2).
-  K. Hämäläinen, A. Kallonen, V. Kolehmainen, M. Lassas, K. Niinimäki, S. Siltanen, 2013. *Sparse Tomography*, *SIAM J Sci Comput*, 35(3).

